

Amendments to the Claims:

This listing of the claims replaces all prior versions of the claims in the application.

Listing of claims:

1. (currently amended) An arm that floats in water, the arm having (a) a surface that is configured to contact a watercraft hull, (b) a length, and (c) a passageway that is not centered along the length, where the surface has a pre-contact shape that is at least one of substantially flat and bowed inwardly.
2. (original) The arm of claim 1, where the watercraft hull is part of a watercraft that has a longitudinal watercraft axis, and the passageway is substantially parallel to the longitudinal watercraft axis.
3. (canceled)
4. (original) The arm of claim 1, where the arm is made substantially completely of synthetic material.
5. (currently amended) The arm of claim 1 An arm that floats in water, the arm having (a) a surface that is configured to contact a watercraft hull, (b) a length, and (c) a passageway that is not centered along the length, where the passageway extends between two rotation-restricting openings.

6. (currently amended) An arm that floats in water and that has a surface that is configured to contact a watercraft hull, the surface having a pre-contact shape that is at least one of either substantially flat and or bowed inwardly, and the arm being configured to be pivotally coupled to a watercraft docking structure.

7. (currently amended) The arm of claim 6, where the arm also has a second surface that is configured to contact a watercraft hull, the second surface having a pre-contact shape that is at least one of either substantially flat and or bowed inwardly.

8. (original) The arm of claim 6, where the arm is made substantially completely of synthetic material.

9. (original) The arm of claim 6, where the arm has (i) a length and (ii) an opening that is not centered along the length.

10. (original) The arm of claim 9, where the opening is a rotation-restricting opening.

11. (original) The arm of claim 6, where the arm has a length, a longitudinal axis oriented along the length, and a passageway that is substantially perpendicular to the longitudinal axis.

12. (currently amended) An arm that floats in water and is configured to (a) contact a watercraft hull with a surface that is generally wider than long, the arm being and (b) be pivotally

coupled to a frame that is pivotally coupled to a watercraft-lifting system ~~watercraft docking structure~~.

13. (original) The arm of claim 12, where the arm also is configured to contact a watercraft hull with a second surface that is generally wider than long.

14. (original) The arm of claim 12, where the arm is made substantially completely of synthetic material.

15. (original) The arm of claim 12, where the arm has (i) a length and (ii) an opening that is not centered along the length.

16. (currently amended) ~~The arm of claim 15~~ An arm that floats in water and is configured to (a) contact a watercraft hull with a surface that is generally wider than long, and (b) be pivotally coupled to a watercraft docking structure, where the arm has (i) a length and (ii) an opening that is not centered along the length, and where the opening is a rotation-restricting opening.

17. (original) The arm of claim 12, where the arm has a length, a longitudinal axis oriented along the length, and a passageway that is substantially perpendicular to the longitudinal axis.

18. (currently amended) An arm that floats in water and is configured to (a) contact a watercraft hull with a first surface that is non-rolling and with a second surface that is non-rolling, and (b) be pivotally coupled to a watercraft docking structure.

19. (canceled)

20. (original) The arm of claim 18, where the arm is made substantially completely of synthetic material.

21. (original) The arm of claim 18, where the arm has (i) a length and (ii) an opening that is not centered along the length.

22. (currently amended) ~~The arm of claim 21~~ An arm that floats in water and is configured to (a) contact a watercraft hull with a surface that is non-rolling, and (b) be pivotally coupled to a watercraft docking structure, where the arm has (i) a length and (ii) an opening that is not centered along the length, and where the opening is a rotation-restricting opening.

23. (original) The arm of claim 18, where the arm has a length, a longitudinal axis oriented along the length, and a passageway that is substantially perpendicular to the longitudinal axis.

24. (currently amended) An apparatus comprising:

a pair of float arms configured to help center a watercraft having a longitudinal watercraft axis, each float arm having a passageway that is substantially parallel to the longitudinal watercraft axis; and

a frame to which both float arms are pivotally coupled, the frame having a bar to which one of the float arms is pivotally coupled, the bar being long enough for at least two float arms to be pivotally coupled to the bar.

25. (canceled)

26. (currently amended) The apparatus of claim 245, further including:
a second pair of float arms pivotally coupled to the frame.

27. (currently amended) An apparatus comprising:
a pair of float arms configured to help center a watercraft having a longitudinal watercraft axis, at least one of the float arms having a length and a first structure that is configured to be pivotally coupled to a watercraft docking structure, the first structure being not centered along the length; and
a frame to which both float arms are pivotally coupled, the frame having a bar to which one of the float arms is pivotally coupled, the bar being long enough for at least two float arms to be pivotally coupled to the bar.

28. (original) The apparatus of claim 27, where the float arm having the first structure also has a portion having a width, and the first structure is a wall defining a passageway that spans the width.

29. (canceled)

30. (currently amended) The apparatus of claim 27, further including:
a second pair of float arms pivotally coupled to the frame.

31. (currently amended) An apparatus useful for centering a watercraft, comprising:
a first float arm having a first float arm length, the first float arm being configured to (a)
be pivotally coupled to a watercraft docking structure, and (b) pivot about a first
axis that is not centered along the first float arm length; and
a second float arm ~~configured~~ having a second float arm length, the second float arm
being configured to (a) be pivotally coupled to a watercraft docking structure, and
(b) pivot about a second axis that is not centered along the second float arm
length, the first and second axes being laterally spaced apart from each other;
where the first and second float arms are configured to be pivotally coupled to a frame
that is configured to be pivotally coupled to a trailer.

32. (canceled)

33. (currently amended) The apparatus of claim 312, where the first and second float arms are pivotally coupled to the frame, the first float arm pivots about the first axis, and the second float arm pivots about the second axis.

34. (original) The apparatus of claim 33, where (i) the frame includes a back portion to which the first and second float arms are pivotally coupled, and a front portion that is pivotally connected to the back portion along a lateral axis that is substantially perpendicular to the first and second axes; and (ii) the front portion of the frame is configured to be pivotally coupled to a trailer.

35. (original) The apparatus of claim 33, where the frame is configured to pivot about a frame axis that is substantially perpendicular to the first and second axes.

36. (original) The apparatus of claim 33, where (i) the frame includes two substantially parallel bars, (ii) the first float arm pivots about one of the substantially parallel bars, and (iii) the second float arm pivots about the other substantially parallel bar.

37. (original) The apparatus of claim 36, where one of the parallel bars comprises different bars connected together.

38. (original) The apparatus of claim 36, where (i) the first float arm includes a first float arm passageway through which one of the substantially parallel bars runs, and (ii) the second

float arm includes a second float arm passageway through which the other substantially parallel bar runs.

39. (original) The apparatus of claim 31, where (i) the first float arm includes a first float arm passageway that is not centered along the first float arm length, and (ii) the second float arm includes a second float arm passageway that is not centered along the second float arm length.

40. (original) The apparatus of claim 36, where the first and second float arms comprise a pair of float arms, and the device also includes:

a second pair of float arms pivotally coupled to the frame, one float arm from the second pair being pivotally coupled to one of the substantially parallel bars, and the other float arm from the second pair being pivotally coupled to the other substantially parallel bar.

41. (original) The apparatus of claim 40, the apparatus including at least three pairs of float arms pivotally coupled to the frame.

42. (original) The apparatus of claim 41, the apparatus including at least four pairs of float arms pivotally coupled to the frame.

43. (currently amended) ~~The apparatus of claim 31, An apparatus useful for centering a watercraft, comprising:~~

a first float arm having a first float arm length, the first float arm being configured to (a) be pivotally coupled to a watercraft docking structure, and (b) pivot about a first axis that is not centered along the first float arm length; and

a second float arm having a second float arm length, the second float arm being configured to (a) be pivotally coupled to a watercraft docking structure, and (b) pivot about a second axis that is not centered along the second float arm length, the first and second axes being laterally spaced apart from each other;

where the first and second float arms are configured to be pivotally coupled to a frame that is configured to be pivotally coupled to a watercraft-lifting system.

44. (original) The apparatus of claim 43, where the first and second float arms are pivotally coupled to the frame.

45. (original) The apparatus of claim 44, where the frame is configured to be pivotally coupled to a lift tank system.

46. (original) The apparatus of claim 45, where the frame is configured to pivot about a frame axis that is substantially perpendicular to the first and second axes.

47. (original) The apparatus of claim 44, where (i) the frame includes two substantially parallel bars, (ii) the first float arm pivots about one of the substantially parallel bars, and (iii) the second float arm pivots about the other substantially parallel bar.

48. (original) The apparatus of claim 47, where one of the parallel bars comprises different bars connected together.

49. (original) The apparatus of claim 47, where (i) the first float arm includes a first float arm passageway through which one of the substantially parallel bars runs, and (ii) the second float arm includes a second float arm passageway through which the other substantially parallel bar runs.

50. (original) The apparatus of claim 43, where (i) the first float arm includes a first float arm passageway that is not centered along the first float arm length, and (ii) the second float arm includes a second float arm passageway that is not centered along the second float arm length.

51. (original) The apparatus of claim 47, where the first and second float arms comprise a pair of float arms, and the apparatus also includes:

a second pair of float arms pivotally coupled to the frame, one float arm from the second pair being pivotally coupled to one of the substantially parallel bars, and the other float arm from the second pair being pivotally coupled to the other substantially parallel bar.

52. (original) The apparatus of claim 51, the apparatus including at least three pairs of float arms pivotally coupled to the frame.

53. (original) The apparatus of claim 52, the apparatus including at least four pairs of float arms pivotally coupled to the frame.

54. (original) The apparatus of claim 53, the apparatus including at least five pairs of float arms pivotally coupled to the frame.